

# Designing an Advanced Drivers Assistance System Based on Emotion and Gesture Recognition using Soft Computing Techniques

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## Abstract

Facial expression recognition based on holistic and feature extraction playing a vital role in Advance Driver Assistance System (ADAS). In this paper, uses soft computing tool, named fuzzy rule base system which simultaneously works on recognition facial gesture and emotional recognition. Due to large number of rad accident takes place during driving for the cause of drowsiness or tired mood. The objective of this paper to design a system in which due to less attention on driving due to any reasons ,vehicle will automatically switch to automatic mode and novel fuzzy system created based on number of rules define through the analysis of various condition and expression also detect facial gesture through the eyes motion and lips. This paper classifying specifies emotions of human like anger,sad,surprise and based on classifies emotions, shifted to automatic designed mode of vehicle. The propose system provides 94.8% accuracy to for facial gesture with action and facial expression and emotion recognition

**Keywords:** FBS (Fuzzy Rule Based System), ADAS (Advance Driver Assistance System), Facial gesture emotion recognition, Human Centered Transportation System (HCTS), FERS (Facial Expression Recognition System)

## Introduction

To reduce the large number of road accident, Advance Driver Assistance System (ADAS) is used to improve or design reliable driving system. The driver has a capability to recognize safety protocols when the ADAS installed in his vehicle. In the case of emergencylike, may be driver is tired or emotionally down this proposed system will take action according to the situation. Design a System should be good enough so that it automatically shifted or act accordingly. This frameworkjudges ADAS'safety protocols and act accordingly.

This paper approaches a new system named Human Cantered Transportation System (HCTS) which is tracking parallel facial gesture and emotion recognition. FERS (Facial Expression Recognition System) is used to communicate human expression and emotion to the system. This proposed system works in steps where first step is used to tracking the face and then extract features from the face. During expression recognition, feature extraction plays a key role because it is used to distinguish different emotion state. By detecting driver facial expression and gesture recognition, a large number of road accidents can be reduced. So facial expression recognition system and gesture recognition system plays a various significant contribution in ADAS and HCTS.

## Review of Literature

Advanced driver assistance systems (ADAS) is used to develop an automatic system for vehicles. This system is used for safety purpose and for better driving .This is basically used to avoid collisions and accidents.Beacuzsthis system alertsthe driver during driving in angry, sad or related emotions. Because these emotions disturb the driving. Result is accident.This system can be apply in smart phone or in anyone 'car so that other 'driver getting alert msg ,which can keep the driver in correct lane so that rate of accident is become low.

It is one of the most growing sysetem in designing of advanced vehicle. Newly designed Next-generation ADAS uses a Wi-Fi technology.

Designed such system are comes into V2V and Car to infrastructure category.[7]

**Aim of the Study**

Car security innovation is truly simple to wrap your head around, yet propelled driver help frameworks (ADAS) are somewhat harder to bind. Now, the level headed discussion about whether non-freezing stopping devices are extremely important is basically non-existent, however most advancements delegated ADAS are still observed as extravagances or notwithstanding diverting interests.

From the past few years, some latest driver assistance systems are been used. These systems are giving noticeable outputs like road safety and enhanced driving experience. GPS is the most common method which was invented in 1990's. Nowadays, drivers don't find paper maps as the efficient technique but the newest driver technologies are much beneficial. All these systems are continuously judged by the specialists and suggestions for their improvement are also given time to time.

Out of these systems few systems are important enough that you may get them in your next car rest of them may be dropped. ADAS rely on electronics hence can be controlled by authorities like IEC-61508 and ISO-26262. Many advanced systems are coming in new cars but out of them thirteen different options you may want in your next car.

**Influencing Factors For driver's mental states**

During driving, driver's emotional and mental state is very critical for the sake of safety and security. There are many issues with the driver 'safety'. Because during driving many issues came up with different situations. These situations are based on many factors like-Fatigue, Misperception, Anxiety, Strain, Grief, and Courtesy [5].

**Anger**

It's an intense emotional response which perceived provocation, hurt or threat. Roag Rage is an example of where driver drives the vehicle speedily without thinking of any risks [5].

**Fear**

It's a feeling induced by perceived danger or threat which is a cause of a change in behaviour. This changes driver 'mood and lost the control over the vehicle [6].

**Sadness**

Sadness is an emotional pain which is enough to reduce the driver 'attention.

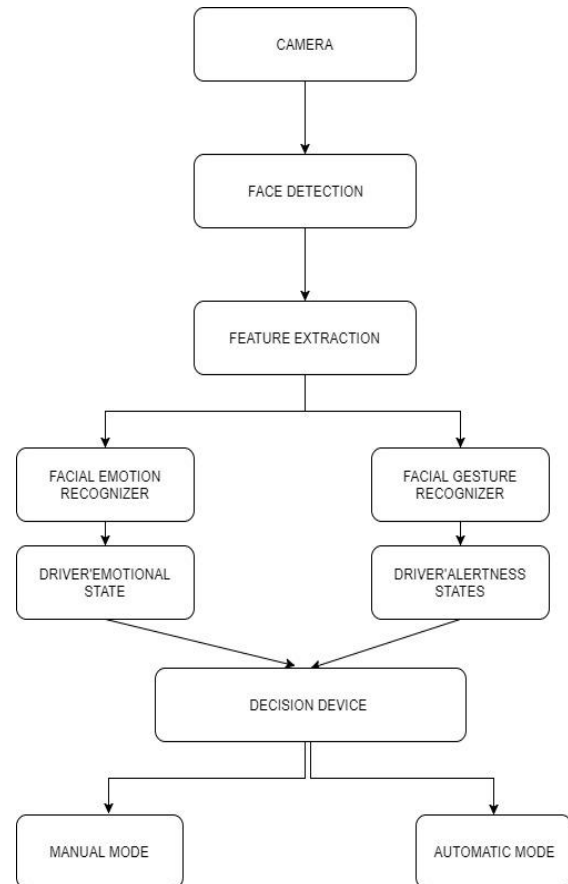
**Fatigue**

It's a feeling of tiredness or exhaustion, in which driver needs rest. de to this driver 'capability is affected.

So it is very important to develop or design such system or mechanism which is used to judge driver 'state and act accordingly. The proposed system uses the concept of Fuzzy Rule Based System and uses pattern recognition in the form of face detection, features extractions and then classifies different emotions.

**Proposed Sysetm' design**

**Figure-1: Proposed Framework for ADAS**



**The Flow of Facial Gesture and Emotion recognition Face Detection**

It's an initial phase in any recognition system. Lots of Research has been research has been done in the region of Face Detection [7-9]. Face detection can be performed in light of a few prompts, for example, Skin shading, Motion, Facial/Head shape, Facial Appearance or mix of these parameters. Skin shading is the fundamental recognizing highlight of human faces. On the off chance that the foundation Environment is legitimate, skin detection can be adequate to find faces in pictures [10]. It can likewise be utilized as a productive preprocessing channel to discover potential skin districts in shading pictures before applying all the more computationally costly face identifiers.

**Facial Features Extraction**

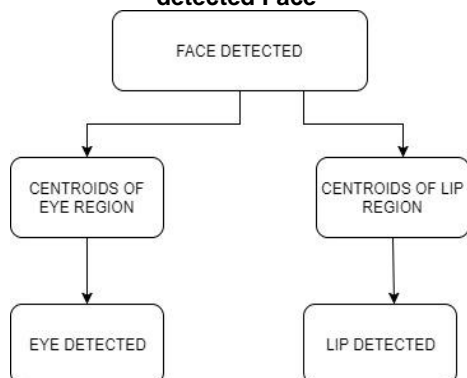
To recognize facial expressions, extract facial features like mouth lips, nose forehead. Three well functional phases are used to define in the system:

1. Face Detection
2. Feature Extraction
3. Emotion Detection

Now, it is expected that there is no earlier information about the area of the eyes and mouth. The underlying edge is utilized to limit the face, eyes and mouth inside the whole information picture. This procedure is rehashed until the point when a worthy

assurance about the places of the eye and mouth is accomplished. Subsequent to distinguishing the highlights of the picture containing a man's face are evaluated, the framework goes into following mode. In this mode, the scan space for face in consequent info outlines is diminished to the little territory encompassing the face district from the main information outline [3].Centroids estimation strategy is utilized for finding eye point The total framework can be depicted through Figure 2.

**Figure-2: Flow Diagram to detect Eye & Lips of the detected Face**



**Facial Gesture tracking based on Eyes and Lips with FBS**

To break down the condition of eye and mouth, the relationship coordinating procedure has been utilized. Once the face and highlights are extricated from each edge, coordinating is done between these highlights and that of the highlights in the main edge. Contingent upon the coordinating, the connection coefficient is evaluated. The general execution of the framework relies upon this coordinating component. On the off chance that the connection coefficient is more than a specific limit, at that point it is viewed as that appropriate coordinating is exists between the highlights. The camera will be situated at a place from where it legitimately concentrates on a man's face. At the point when the underlying casing was taken it is expected that the eyes are open and the mouth is shut. So in the back to back casings the separated points of interest of mouth and eyes are contrasted and those from the underlying casing. In the event that the coordinating variable is not as much as the set limit, it implies that there is no coordinating between the highlights in the present edge with that of the highlights in the main edge [11-12]. The Fuzzy Inference System for Facial Gesture examines eyes and lips activities.

**Emotion Recognition by Fuzzy Logic System**

This exploration work makes utilization of Fuzzy Rule Based System for distinguishing different feelings viz. Upbeat, Angry, Sad and Surprise on account of which the thought regarding the driver's passionate state can be known. Here the contributions to the framework are distinctive Facial Gesture units and the yield compares to the feeling distinguished. The Facial motion unit is only unique scope of ranges like low, low, medium, high and high. The Results for arrangement of various Facial Gesture and Emotion Recognition are such as Eyes

Open: Happy, Sad, Lips Open: Surprised, Lips Closed: Sadis appeared during experiments. The Fuzzy rationale frameworks, which can be utilized to process loose data, give their choices productively. Since they can't consequently obtain the guidelines they use to settle on those choices.

Total no of rules = 3x3x3=27

27 rules are formed on the basis of the inputs and output of the fuzzy system. After running the program several times for different samples, it has been found that only four rules shown are optimum while the remaining is redundant to compute the final output.

**Facial Gestutre Tracking and Emotion Recognition**

The FBS framework characterized above for Facial Gesture following and Emotion acknowledgment than utilized for synchronous framework. Here picture is given as a contribution to the framework from which face will be distinguished and after that zone will be ascertained from the relating Centroids of eye and lip locale. This estimation of zone is then passed to the above FBS Systems which will give us the after effect of synchronous Facial Gesture following and Emotion acknowledgment as indicated by the tenets characterized.

**Summary of Results & Conclusion**

The FBS framework for various Facial Gestures and Emotions, described in section II is actually implemented on MATLAB. Above Experiment is completed on 570 diverse picture outline and the tables given beneath demonstrates the outcomes for the same. Each picture outline has measure 640 x 480. The framework gives 91.66% Accuracy for Facial Gesture Tracking and 90% Accuracy for Emotions acknowledgment while utilizing Simultaneous Facial Gesture Tracking and Emotion acknowledgment it gives 94.58% precision.

Input	Type of membership	No of linguistic Variables	Output
Eye state	Triangular	Open /close	Attentive/ sleeping
Lip state	Triangular	Open /close	Yawning/ Normal

**Table I. Result of Different State of FBS**

This exploration work displays an extensive and concurrent discovery of Gesture Recognition and Emotion. The Fuzzy rationale frameworks is discovered a novel way to help the driver and defend the vehicle by exchanging the mode into auto mode during driving. Following Tables are given to underneath demonstrate the comparison of the Facial Gesture and Emotion Recognition results using FBS. It additionally demonstrates the expanding level of Accuracy when Both Facial Gesture and Emotion acknowledgment is done all the while. It is extremely well accommodating for identification of a crisis to changing vehicle control from manual to programmed mode.

Table II Result of Different Facial Gesture Using FBS

Facial Gesture Recognised	No. of frames	Current detection	Error frames	% Accuracy	Controller
Attentive & Alert	63	66	6	94.76	Manual Mode
Sleeping	35	34	7	94.91	Automatic mode
Yawning	26	26	4	92.98	Automatic mode

Table III. Result of Different Facial Gesture & Emotions Recognition Using FBS

Different Combination of Facial Gesture and Emotions	No. of frames	Current detection	Error frames	% Accuracy	Controller
Attentive & happy	82	77	5	91.55	Manual mode
Less attentive and sad	45	38	6	93.18	Automatic mode
Medium attentive and fear	87	73	8	94.25	Manual mode
Least attentive & Anger	47	33	2	95.98	Automatic mode

Table IV. Result of Different Facial Gesture & Emotions Using FBS with Different Cameras & Persons

Name of person	Camera used	Different combinations of facial gesture and emotions	No. of frames	Result		% Accuracy
				Correct	Wrong	
Person 1	Camera 1 (DSC-S5000)	Attentive & happy	25	26	4	90.18
		Less attentive and sad	14	14	4	
		Medium attentive and fear	16	18	2	
		Least attentive & Anger	14	15	4	
	Camera 2 (NIKON coolpix- L21)	Attentive & happy	26	23	3	94.79
		Less attentive and sad	19	18	5	
		Medium attentive and fear	24	15	4	
		Least attentive & Anger	15	16	5	
Person 2	Camera 1 (DSC-S5000)	Attentive & happy	26	23	2	90.22
		Less attentive and sad	19	17	2	
		Medium attentive and fear	23	13	3	
		Least attentive & Anger	17	17	3	
	Camera 2 (NIKON coolpix- L21)	Attentive & happy	27	25	4	92.62
		Less attentive and sad	16	16	2	
		Medium attentive and fear	18	13	1	
		Least attentive & Anger	16	12	4	

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